

# Empirical Likelihood

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## Today: Research topics

- 1) Hybrids with parametric likelihoods
- 2) Bayes and EL
- 3) Log concavity
- 4) Escaping from the hull
- 5) Sparse likelihoods
- 6) Convex objective; bilinear constraint
- 7) Regression and convexity

These are areas that are either new, have potential for new uses, or are ripe for improvement.

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## These lectures

- I) Basics of empirical likelihood
- II) Estimating equations
- III) Research frontier ✓

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## EL hybrids (mostly Jing Qin)

Part of the problem is parametric

We want to use that knowledge

The rest of the problem is non-parametric

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## One parametric sample, one not

$\mathbf{Y}$  well studied and has parametric distribution  
 $\mathbf{X}$  new and/or does not follow parametric distribution

$$\mathbf{X}_i \sim F, \quad i = 1, \dots, n$$

$$\mathbf{Y}_j \sim G(\mathbf{y}; \theta), \quad j = 1, \dots, m$$

$$0 = \int \int h(\mathbf{x}, \mathbf{y}, \phi) dF(\mathbf{x}) dG(\mathbf{y}; \theta)$$

e.g.  $\phi = \mathbb{E}(\mathbf{Y}) - \mathbb{E}(\mathbf{X})$

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## Parametric model for data ranges

$$\mathbf{X} \sim \begin{cases} f(\mathbf{x}; \theta) & \mathbf{x} \in P_0 \\ ??? & \mathbf{x} \notin P_0 \end{cases}$$

Examples

- Extreme values, exponential tails on  $P_0 = [T, \infty)$  something else below  $T$
- Normal data on  $P_0 = [-T, T]$  with outliers outside

$$L = \prod_{i=1}^n f(\mathbf{x}_i; \theta)^{1_{\mathbf{x}_i \in P_0}} w_i^{1_{\mathbf{x}_i \notin P_0}}$$

Define  $\mathcal{R}$  using

$$1 = \int_{P_0} dF(\mathbf{x}; \theta) + \sum_{i=1}^n w_i 1_{\mathbf{x}_i \notin P_0}$$

Qin & Wong get a  $\chi^2$  limit for means

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## Multiply the likelihoods

$$L(F, \theta) = \prod_{i=1}^n F(\{\mathbf{x}_i\}) \prod_{j=1}^m g(\mathbf{y}_j; \theta)$$

$$R(F, \theta) = L(F, \theta) / L(\hat{F}, \hat{\theta})$$

$$\mathcal{R}(\phi) = \max_{F, \theta} R(F, \theta) \quad \text{such that}$$

$$0 = \sum_{i=1}^n w_i \int h(\mathbf{x}_i, \mathbf{y}, \phi) dG(\mathbf{y}; \theta)$$

Qin gets a  $\chi^2$  limit

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## More hybrids

Parametric	Nonparametric	
$g(\mathbf{y}   \mathbf{x}; \theta)$	$\mathbf{X} \sim F$	
$\mathbf{X} \sim f(\mathbf{x}; \theta)$	$\mathbf{Y}   \mathbf{X} = \mathbf{x} \sim G_{\mathbf{x}}$	Few $\mathbf{x}$ vals
$\mathbf{X} \sim f(\mathbf{x}; \theta)$	$(\mathbf{Y} - \mu(\mathbf{x})) / \sigma(\mathbf{x}) \sim G$	

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## Bayesian empirical likelihood (Lazar)

Prior  $\theta \sim \pi(\theta)$

$x \sim F$  nonparametric

Posterior  $\propto \pi(\theta)\mathcal{R}(\theta)$

Here we have informative prior nonparametric likelihood

Reverse of a common practice

Posterior regions asymptotically properly calibrated

Maybe it can be justified via least favorable families

Schennach (2005) multiplies an exponential likelihood by a prior.

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## Log concavity

There is an MLE for the problem of maximizing  $\prod_{i=1}^n f(x_i)$  where  $f$  is a log concave density on  $\mathbb{R}^d$ .

Suppose now that we maximize this likelihood subject to

$$\int_{\mathbb{R}^d} \mathbf{x} f(\mathbf{x}) d\mathbf{x} = \mu, \quad \text{or} \quad \int_{\mathbb{R}^d} m(\mathbf{x}, \theta) f(\mathbf{x}) d\mathbf{x} = 0$$

Will the result yield a  $\chi^2$  calibration?

How will we compute it?

The MLE density  $\hat{f}$  is supported on the convex hull of  $\mathbf{x}_i$  and so the hull issue (below) will be relevant when  $d$  is large

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## Approximate Bayesian Computation

ABC is used in problems where the likelihood cannot be computed.

For example, suppose we have a model with parameter  $\theta$  for how biological populations may have evolved over a long time period. But we only have data on the present. There may be no good way to evaluate the probability of the present as a function of  $\theta$ .

In ABC we sample  $\theta_1, \dots, \theta_N$  from the prior distribution on  $\theta$  and then data  $\mathbf{X}$  from its distribution given  $\theta$ . If  $\mathbf{X}_i$  is close to the observed value  $\mathbf{X}^*$  then we retain  $\theta_i$  and give it a 'weight' that is inversely proportional to some  $\text{dist}(\mathbf{X}_i, \mathbf{X}^*)$ .

The normalized weights are interpreted as a posterior distribution on  $\theta$ . There are many versions.

Mengersen, Pudlo & Robert (2013) use empirical likelihood for an ABC-like algorithm, when the parameter is defined by estimating equations.

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## Probability $\mu_0$ in the hull

$$\mathcal{H} = \left\{ \sum_{i=1}^n w_i \mathbf{x}_i \mid w_i \geq 0, \sum_{i=1}^n w_i = 1 \right\}$$

Wendel (1962)

If distn of  $\mathbf{X}_i$  symmetric about  $\mu$  then

$$\begin{aligned} \Pr(\mu \notin \mathcal{H}) &= \sum_{k=0}^{d-1} \binom{n-1}{k} \left(\frac{1}{2}\right)^{n-1} \\ &= \Pr(\text{Bin}(n-1, 1/2) < d) \end{aligned}$$

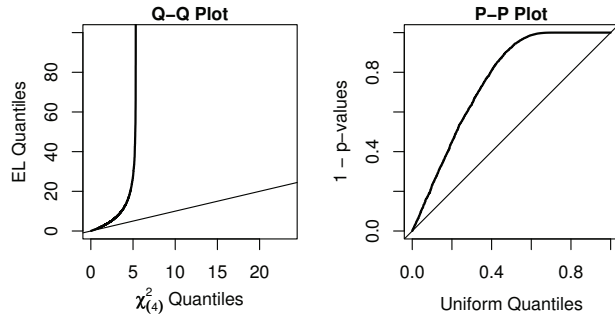
$d-1$  or fewer heads in  $n-1$  trials

NB: a set of  $n-1$  independent coin toss events corresponding to this result has yet to be exhibited.

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# Plain EL under-coverage (extreme case)

d = 4, n = 10  
Normal



Emerson & O (2009)

Vertical asymptote from atom at  $+\infty$  for  $-2 \log \mathcal{R}(\mu_0)$ .

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# Growing dimension

Hjort, McKeague & Van Keilegom (2009)

Consider EL for dimension  $p$  growing with  $n$

Bounded  $\mathbf{X}_{n,i}$  IID mean 0 variance  $\Sigma_n$  with eigenvalues in  $[A, B] \subset (0, \infty)$

Key condition for  $\chi^2$  limit is  $\frac{p^3}{n} \rightarrow 0$

For  $q > 2$  moments  $\frac{p^{3+6/(q-2)}}{n} \rightarrow 0$

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# Penalized EL

Bartolucci (2007) gives 15 points in  $\mathbb{R}^4$  from  $\chi^2_{(1)}$ . The mean is not in the hull.

Bootstrapping:  $\bar{x}$  is not in the hull of resampled data 30% of the time.

relax the constraint

$$L^\dagger(\mu, h) = \max_w \prod_{i=1}^n w_i \times e^{-n\delta(\nu-\mu)/(2h^2)}$$

where  $\nu = \sum_i w_i \mathbf{x}_i$  and  $\delta(\nu - \mu) = (\nu - \mu)^T V^{-1}(\nu - \mu)$  for  $V$  positive definite (eg sample covariance)

This favors  $\nu$  close to  $\mu$  but does not enforce it. There's a  $\chi^2$  limit if  $h = O(n^{-1/2})$

Lahiri & Mukhopadhyay (2012) avoid using a sample covariance extend to very large  $p$  including some  $p > n$

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# Escape from the hull

Idea: extend the sample to ensure that  $\mu \in \mathcal{H}$

If we knew a support set for  $F$  we could use it.

Or, add an artificial point (undata)  $\mathbf{x}_{n+1}$ . Now,

$$T(F) = \sum_{i=1}^{n+1} w_i \mathbf{x}_i, \text{ and,}$$

$$L(F) = \prod_{i=1}^n w_i, \text{ or,}$$

$$L(F) = \prod_{i=1}^{n+1} w_i.$$

The second version is easier computationally and asymptotically the same (if  $\|\mathbf{x}_{n+1}\|$  reasonable).

Chen, Variyath & Abraham (2008) originate this approach.

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## Adjusted empirical likelihood

Chen, Variyath & Abraham (2008) use

$$\begin{aligned} \mathbf{x}_{n+1} &= \mu - a_n(\bar{\mathbf{x}} - \mu), \quad a_n = \log(n)/2 \\ a_n &= o_p(n^{2/3}) \quad \text{preserves 1st order asymptotics} \end{aligned}$$

Note: new point  $\mathbf{x}_{n+1}$  depends on  $\mu$

Now  $\mu$  is between  $\bar{\mathbf{x}}$  and  $\mathbf{x}_{n+1}$ :

$$\mu = \frac{\mathbf{x}_{n+1} + a_n \bar{\mathbf{x}}}{1 + a_n}$$

Hull of  $\mathbf{x}_1, \dots, \mathbf{x}_{n+1}$  contains  $\mu$

## Not all is well yet

Let  $\mathcal{R}^*$  be adjusted profile empirical likelihood. Then we can show:

$$-2 \log \mathcal{R}^*(\mu) \leq -2 \left[ n \log \left( \frac{(n+1)a_n}{n(a_n+1)} \right) + \log \left( \frac{n+1}{a_n+1} \right) \right]$$

which is bounded, even if  $\|\mu\| \rightarrow \infty$ .

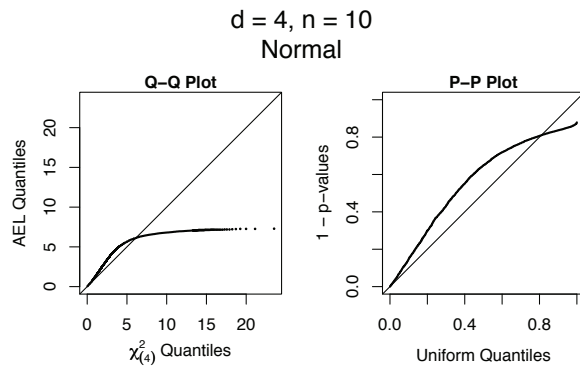
Opposite problem from  $\log \mathcal{R}(\mu)$  which diverged at finite  $\|\mu\|$ .

Instead of a bounded 100% region we can get all of  $\mathbb{R}^d$  at less than 100% confidence.

Extreme example ctd.

$n = 10, d = 4, 88.1\%$  region is  $\mathbb{R}^4$ .

## Adjusted EL coverage (extreme case)



Emerson & O (2009)

## Balanced adjusted empirical likelihood

Dissertation: Emerson (2009)

- 1) Add 2 points  $\mathbf{x}_{n+1}$  and  $\mathbf{x}_{n+2}$
- 2)  $(\mathbf{x}_{n+1} + \mathbf{x}_{n+2})/2 = \bar{\mathbf{x}}$  (preserving sample mean)
- 3) farther new points if  $\mu - \bar{\mathbf{x}}$  is a direction where the sample varies a lot

Add points

$$\begin{aligned} \mathbf{x}_{n+1} &= \mu - s c_{u^*} u^* \\ \mathbf{x}_{n+2} &= 2\bar{\mathbf{x}} - \mu + s c_{u^*} u^* \end{aligned}$$

where

$$u^* = \frac{\bar{\mathbf{x}} - \mu}{\|\bar{\mathbf{x}} - \mu\|} \quad c_{u^*} = (u^{*\top} S^{-1} u^*)^{-1/2}$$

$$S = \frac{1}{n-1} \sum_{i=1}^n (\mathbf{x}_i - \bar{\mathbf{x}})(\mathbf{x}_i - \bar{\mathbf{x}})^\top \quad s \approx 1.9$$

## Choice of $s$

Choice of  $s$  is based on empirical work. The best  $s$  depends (weakly) on  $d$  eg  
 $s = 1.7$  for  $d = 2$  to  $s = 2.4$  for  $d = 20$

### Animation

Show some slides of [S. Emerson](#) illustrating how  $\mathbf{x}_{n+1}$  and  $\mathbf{x}_{n+2}$  move with  $\mu$

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## Invariance

Let  $A \in \mathbb{R}^{d \times d}$  be non-singular.

Set  $\tilde{\mathbf{x}}_i = A\mathbf{x}_i$  and  $\tilde{\mu} = A\mu$ .

Let  $C$  be the balanced adjusted empirical likelihood region for  $\mu_0$  based on  $\mathbf{x}_1, \dots, \mathbf{x}_n$ .

Let  $\tilde{C}$  be the balanced adjusted empirical likelihood region for  $\tilde{\mu}_0 = A\mu_0$  based on  $\tilde{\mathbf{x}}_1, \dots, \tilde{\mathbf{x}}_n$ .

Then  $\mu \in C \iff \tilde{\mu} \in \tilde{C}$ .

[Emerson & O \(2009\)](#) Proposition 4.1.

Hotelling's  $T^2$  and the original EL are also invariant this way.

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## Related

Independently [Liu & Chen \(2009\)](#) also added 2 points.

Their 2 points were designed to improve Bartlett correction.

Ours were tuned to give good small sample coverage in high dimensions.

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## Avoiding the boundedness

Recall  $-2 \log \mathcal{R}^*$  was bounded.

The new criterion  $-2 \log \mathcal{R}^{**}$  is unbounded.

The ultimate cause is that

$\|\mathbf{x}_{n+1} - \mu\|$  is proportional to  $\|\tilde{\mathbf{x}} - \mu\|$  in AEL but is of constant order in BAEL

The larger  $\|\mathbf{x}_{n+1} - \mu\|$  in AEL means that less weight needs to go there.

Less weight there  $\dots$  allows more weight on the other  $n$  points and a higher likelihood.

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## Connection to $T^2$

Recall

$$\mathbf{x}_{n+1} = \mu - sc_{u^*} u^* \quad \mathbf{x}_{n+2} = 2\bar{\mathbf{x}} - \mu + sc_{u^*} u^*, \quad \text{where}$$

$$u^* = \frac{\bar{\mathbf{x}} - \mu}{\|\bar{\mathbf{x}} - \mu\|} \quad \text{and} \quad c_{u^*} = (u^{*\top} S^{-1} u^*)^{-1/2}.$$

Theorem 4.2

$$\lim_{s \rightarrow \infty} \frac{2ns^2}{(n+2)^2} (-2 \log \mathcal{R}^{**}(\mu)) = T^2(\mu)$$

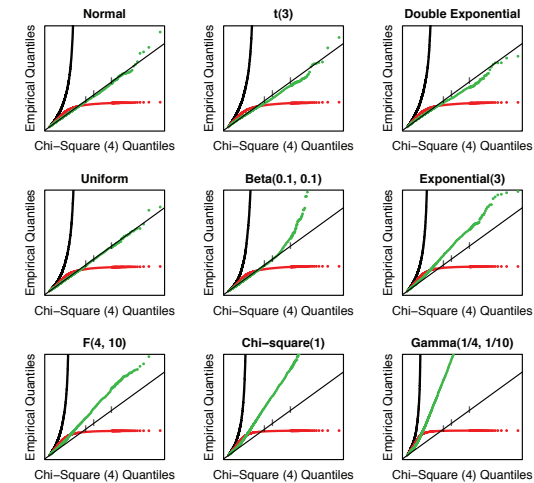
Emerson & O (2009)

## Comments

- 1) More examples in the article
- 2) Good calibration for distributions with shorter tails
- 3) High kurtosis is harder
- 4) Even there the calibration is almost linear so a Bartlett correction could help a lot
- 5) Exact nonparametric CI.s for the mean are unobtainable Bahadur & Savage (1956)

### Quantile-Quantile Plots

$d = 4, n = 10$



Emerson & O (2009)

## Infinitely many estimating equations

Symmetry:

$$\mathbb{E}(|X - \mu|^k \text{sign}(X - \mu)) = 0, \quad \forall k \geq 1$$

Independence:

$$\mathbb{E}(\phi(X)\psi(Y)) = \mathbb{E}(\phi(X))\mathbb{E}(\psi(Y)), \quad \forall \phi(\cdot), \psi(\cdot)$$

## EL with sparse likelihoods

Replacing  $-2 \sum_{i=1}^n \log(nw_i)$  by some multiple of  $\sum_{i=1}^n |nw_i - 1|$  should lead to many data points with  $w_i = 1/n$  exactly. The exceptions may be interpretable.

$L_\infty$  version

$$\max_{1 \leq i \leq n} |nw_i - 1|$$

Using this criterion should often lead to a subset of observations with  $w_i$  at some maximal level and another subset at a minimal level. That pattern may be revealing.

## Multisample EL

Chapter 11.4 of the text "Empirical likelihood" looks at a multi-sample setting.

Observations  $\mathbf{X}_i \stackrel{\text{iid}}{\sim} F$  for  $i = 1, \dots, n$  independent of  $\mathbf{Y}_j \stackrel{\text{iid}}{\sim} G$  for  $j = 1, \dots, m$ . The likelihood ratio is

$$\prod_{i=1}^n \prod_{j=1}^m (nu_i)(mv_j)$$

with  $u_i \geq 0, v_j \geq 0, \sum_i u_i = 1, \sum_j v_j = 1$  and

$$\sum_i \sum_j u_i v_j h(\mathbf{x}_i, \mathbf{y}_j, \theta) = 0 \tag{1}$$

For example:  $h(X, Y, \theta) = 1_{X-Y > \theta} - 1/2$ . The computational problem is a challenge. The log likelihood is convex but constraint (1) is bilinear. So computation is awkward.

## Profiling for regression

Maximize  $\sum_{i=1}^n \log(nw_i)$  subject to  $w_i \geq 0, \sum_i w_i = 1$

$$\sum_i w_i (Y_i - \mathbf{x}_i^T \beta) \mathbf{x}_i = 0$$

and  $\beta_j = \beta_{j0}$ .

Not quite convex optimization

The free variables are  $\beta_k$  for  $k \neq j$  as well as  $w_1, \dots, w_n$ .

The computational challenge comes from **bilinearity** of the constraint.

If  $\beta$  is held fixed the normal equation constraint is linear in  $w$  and vice versa.

## Regression again

$$Y \approx \mathbf{x}^T \beta, \quad \mathbf{x} \in \mathbb{R}^d, \quad y \in \mathbb{R}$$

Estimating equations\*

$$\mathbb{E}((Y - \mathbf{x}^T \beta) \mathbf{x}) = 0$$

Normal equations

$$\sum_{i=1}^n (y_i - \mathbf{x}_i^T \beta) \mathbf{x}_i = 0 \in \mathbb{R}^d$$

In principle we let  $\mathbf{z}_i = \mathbf{z}_i(\beta) \equiv (y_i - \mathbf{x}_i^T \beta) \mathbf{x}_i \in \mathbb{R}^d$ , adjoin  $\mathbf{z}_{n+1}$  and  $\mathbf{z}_{n+2}$ , and carry on.

\*residuals  $\epsilon = y - \mathbf{x}^T \beta$  are uncorrelated with  $\mathbf{x}$ .

They have mean zero too, when as usual,  $\mathbf{x}$  contains a constant.



## Regression hull condition

$$\mathcal{R}(\beta) = \sup \left\{ \prod_{i=1}^n n w_i \mid w_i \geq 0, \sum_{i=1}^n w_i = 1, \sum_{i=1}^n w_i (y_i - \mathbf{x}_i^\top \beta) \mathbf{x}_i = 0 \right\}$$

$$\mathcal{P} = \mathcal{P}(\beta) = \{ \mathbf{x}_i \mid y_i - \mathbf{x}_i^\top \beta > 0 \} \quad \mathbf{x} \text{ with pos resid}$$

$$\mathcal{N} = \mathcal{N}(\beta) = \{ \mathbf{x}_i \mid y_i - \mathbf{x}_i^\top \beta < 0 \} \quad \mathbf{x} \text{ with neg resid}$$

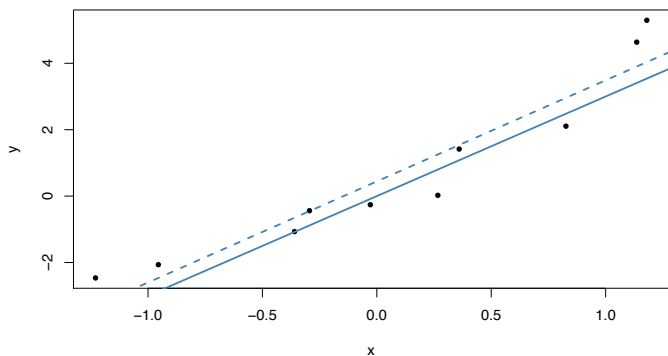
### Convex hull condition O (2000)

$$\text{chull}(\mathcal{P}) \cap \text{chull}(\mathcal{N}) \neq \emptyset \implies \beta \in C(0)$$

For  $\mathbf{x}_i = (1, t_i)^\top \in \mathbb{R}^2$   $\mathcal{P}$  and  $\mathcal{N}$  are intervals in  $\{1\} \times \mathbb{R}$ .

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Example regression data



$$Y = \beta_0 + \beta_1 X + \sigma \epsilon \quad \beta = (0, 3)^\top, \sigma = 1$$

$\beta$  solid  $\hat{\beta}$  dashed

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## Converse

Suppose that  $\tau \notin \{t_1, \dots, t_n\}$  and

$$\text{Sign}(y_i - \beta_0 - \beta_1 t_i) = \begin{cases} 1, & t_i > \tau \\ -1, & t_i < \tau \end{cases}$$

Suppose also that

$$\sum_i w_i \begin{pmatrix} 1 \\ t_i \end{pmatrix} (y_i - \beta_0 - \beta_1 t_i) = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

Then

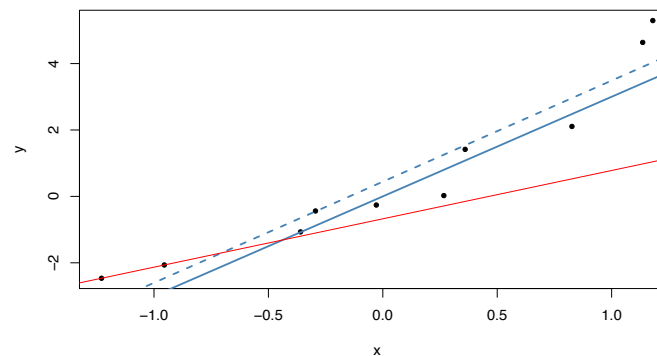
$$\sum_i w_i (y_i - \beta_0 - \beta_1 t_i) (t_i - \tau) = 0$$

But  $(y_i - \beta_0 - \beta_1 t_i) (t_i - \tau) > 0 \forall i$

Therefore the hull condition is **necessary**.

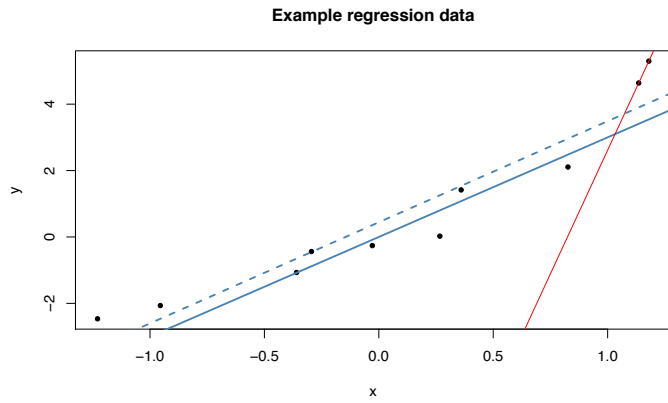
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Example regression data

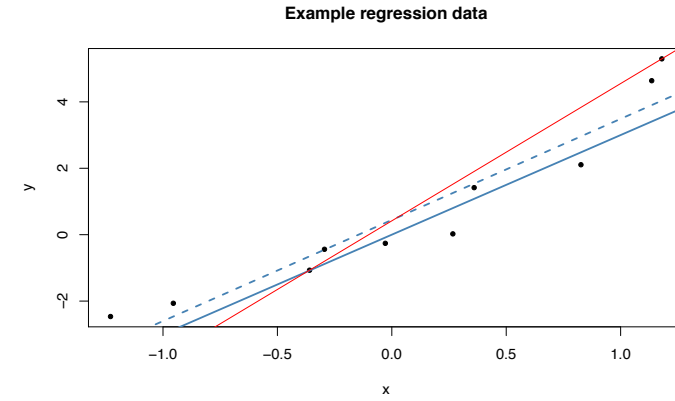


Red line is on boundary of set of  $(\beta_0, \beta_1)$  with positive empirical likelihood

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Another boundary line.

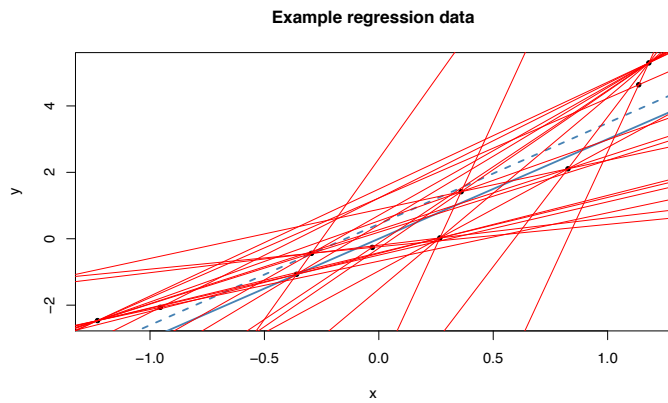


Yet another boundary line.

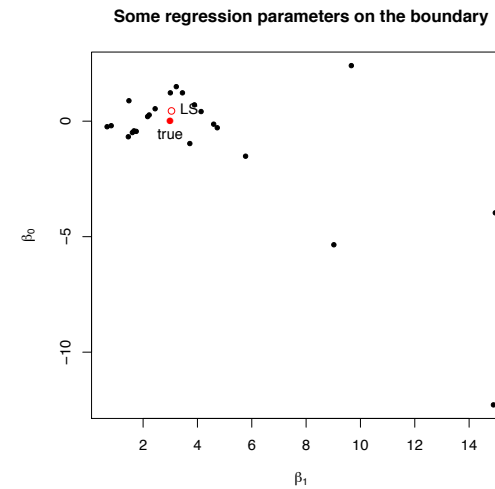
Left side has positive residuals; right side negative.

Wiggle it up and point 3 gets a negative residual  $\implies$  ok.

Wiggle down  $\implies$  NOT ok.



All the boundary lines that interpolate two data points.  
They are a subset of the boundary.



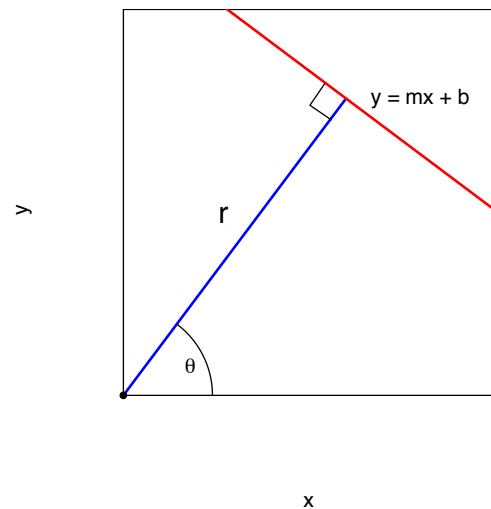
Boundary points  $(\beta_0, \beta_1)$ . Region is not convex.

It is convex in  $\beta_0$  (vertical) for fixed  $\beta_1$  (horizontal).

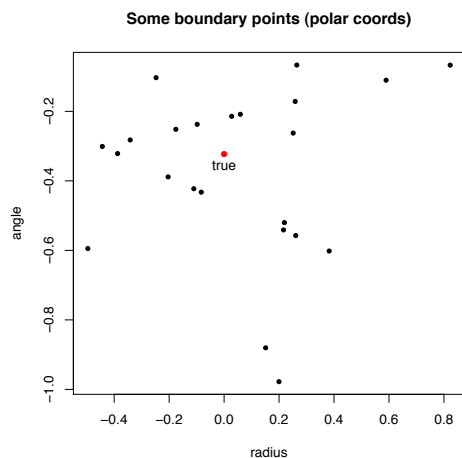
## What is a convex set of lines?

- convex set of  $(\beta_0, \beta_1)$ ?
- convex set of  $(\rho, \theta)$ ? (polar coordinates)
- convex set of  $(a, b)$  ( $ax + by = 1$ )?

## Polar coordinates of a line



## Boundary pts in polar coords



Not convex here either.

## Intrinsic convexity

There is a geometrically intrinsic notion for a convex set of linear flats.

J. E. Goodman (1998) "When is a set of lines in space convex?"

Maybe . . . that can support some computation.

### Dual definition

The set of flats that intersects a convex set  $C \subset \mathbb{R}^d$  is a convex set of flats.

So is the set of flats that intersect **all of**  $C_1, \dots, C_k \subset \mathbb{R}^d$  for convex  $C_j$ .

### Convex functions

This notion of convex set does not yet seem to have a corresponding notion of convex function. There could be quasi-convex functions, those where the level sets are convex. But quasi-convexity is much less powerful computationally than convexity.

## Acknowledgments

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Merci et au revoir!